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$$[-0.25e^{-2t} + 0.25 +$$

$$0.5t] e^{-t} + \frac{1}{2}t^2 + \frac{1}{2}t^3 + \frac{1}{2}t^2$$

$$[r,p,k] = \text{residue}([4,3],[$$

$$1,6,34,0])$$
 The result

$$\text{is } r = [-0.0441 -$$

$$0.3735i, -0.0441 +$$

$$0.3735i, 0.0882], p =$$

$$[-3.0000 + 5.0000i,$$

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$[-3.0000 - 5.0000i, 0]$,

and $k = []$. The

solution is $x(t) =$

$(-0.0441 -$

$0.3735j)e^{(-3+5j)t} +$

$(-0.0441 +$

$0.3735j)e^{(-3-5j)t} +$

0.0882 The solution is

$x(t) = 2e^{-3t} (-0.0441$

$\cos 5t + 0.3735 \sin 5t)$

$+ 0.0882$ (continued

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The open-loop transfer function of the compensated system is $G_c(s)G(s) = \frac{4.946}{s + 4.946} \frac{40}{s + 13.699} \frac{1}{s(s + 2)}$. As $s \rightarrow 0$, the compensator's gain is seen to introduce a gain factor of $4.946/13.699 = 0.361 = 1/\mu$. Thus, in order to preserve C_v

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increase KP by a
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