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The time optimal control problem in unforced discrete systems is studied in this thesis. Comparison is made between the discrete and the continuous control systems by means of minimal time isochrones. Concerning optimal time, it is shown that using discrete control system will take at most one

On time-optimal second order discrete control systems
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A comprehensive treatment of the analysis and design of discrete-time control systems which provides a gradual development of the theory by emphasizing basic concepts and avoiding highly mathematical arguments. The book features comprehensive treatment of pole placement, state observer design, and quadratic optimal control.

Discrete-Time Control Systems: Ogata, Katsuhiko ...

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Discrete control systems, as considered here, refer to the control theory of discrete time Lagrangian or Hamiltonian systems. These discrete time models are based on a discrete variational principle, and are part of the broader field of geometric integration.

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Such a discrete-time control system consists of four major parts: 1 The Plant which is a continuous-time dynamic system. 2 The Analog-to-Digital Converter (ADC). 3 The Controller (μP), a microprocessor with a "real-time" OS. 4 The Digital-to-Analog Converter (DAC). 3 + - r(t) e(t) ADC μP DAC u(t) Plant ? ? y(t) 4

DiscreteTimeControlSystems - ETH Z

Notes for Discrete-Time Control Systems (ECE-520) Fall 2010 by R. Throne The major sources for these notes are † Modern Control Systems, by Brogan, Prentice-Hall, 1991. † Discrete-Time Control Systems, by Ogata. Prentice-Hall, 1995. † Computer Controlled Systems, by Aström and Wittenmark. Prentice-Hall, 1997.

Notes for Discrete-Time Control Systems (ECE-520) Fall 2010

First, digital computers are, by design, discrete-time devices, so discrete-time signals and systems includes digital computers. Second, almost all the important ideas in discrete-time systems apply equally to continuous-time systems. Alas, even discrete-time systems are too diverse for one method of analysis.

Discrete-time Signals and Systems - MIT

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The time interval between two discrete instants is taken to be sufficiently short that the data for the time between them can be approximated by simple interpolation. Discrete-time control systems differ from continuous-time control systems in that signals for a discrete-time control system are in sampled-data form or in digital form.

Discrete time control systems - SlideShare

A comprehensive treatment of the analysis and design

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of discrete-time control systems which provides a gradual development of the theory by emphasizing basic concepts and avoiding highly mathematical arguments. The text features comprehensive treatment of pole placement, state observer design, and quadratic optimal control.

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(available) at all times. A typical continuous time control system is shown in Figure below. (Closed loop continuous-time control system) Discrete time Control System: Discrete time control systems are control systems in which one or more variables can change only at discrete instants of time. These instants, which may be denoted by kT ($k=0,1,2,\dots$)

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